ELASTICITY PROBLEMS IN POLAR COORDINATES (10)

I Main topics

- A Motivation
- B Cartesian Approach
- C Transformation of coordinates
- D Equilibrium equations in polar coordinates
- E <u>Biharmonic equation in polar coordinates</u>
- F <u>Stresses in polar coordinates</u>
- II Motivation
 - A Many key problems in geomechanics (e.g., stress around a borehole, stress around a tunnel, stress around a magma chamber) involve cylindrical geometries. Our reference frame should fit the features we examine.
 - B Introduces the concept of <u>stress concentration</u> due to factors <u>inside</u> a body (as opposed to concentrated boundary loads).
- III <u>Approach</u>
 - A Transform elastic equations from xy form to polar form
 - B Alternative: vector and tensor approaches (see C&P, Ch. 11)
- IV Transformation of coordinates (See Fig. 34.1)
 - A Rectangular to polar:

$$\theta = \tan(y/x)$$
 $r = (x^2 + y^2)^{1/2}$ (10.1)

B Polar to rectangular:

 $x = r \cos \theta$

$$y = r \sin \theta$$

(10.2)

C Stress convention: Still use on-in convention $(\theta_{rr}, \theta_{r\theta}, \theta_{\theta r}, \theta_{\theta \theta})$





V Equilibrium equations in polar coordinates

General form of the terms is $\sigma_{ij} = \{\sigma_{ij} \text{ ref } + (\sigma_{ij} \text{ gradient})(\text{distance})\}.$ $\left(\sigma_{rr} + \frac{\partial \sigma_{rr}}{\partial r} \frac{dr}{2}\right) \left(r + \frac{dr}{2}\right) d\theta - \left(\sigma_{rr} + \frac{\partial \sigma_{rr}}{\partial r} \frac{dr}{2}\right) \left(r + \frac{dr}{2}\right) d\theta + \cos \frac{d\theta}{2} \left(\sigma_{r\theta} + \frac{\partial \sigma_{r\theta}}{\partial \theta} \frac{d\theta}{2}\right) dr - \cos \frac{d\theta}{2} \left(\sigma_{r\theta} - \frac{\partial \sigma_{r\theta}}{\partial \theta} \frac{d\theta}{2}\right) dr + \sin \frac{d\theta}{2} \left(\sigma_{\theta\theta} - \frac{\partial \sigma_{\theta\theta}}{\partial \theta} \frac{d\theta}{2}\right) dr + \sin \frac{d\theta}{2} \left(\sigma_{\theta\theta} - \frac{\partial \sigma_{\theta\theta}}{\partial \theta} \frac{d\theta}{2}\right) dr = 0.$ (10.4)

This equation reduces to

$$\left(2\frac{\partial\sigma_{rr}}{\partial r}\frac{dr}{2}rd\theta\right) + \left(2\sigma_{rr}\frac{dr}{2}d\theta\right) + \left(2\frac{\partial\sigma_{rr}}{\partial \theta}\frac{dr}{2}\frac{dr}{2}d\theta\right) + \left(2\frac{\partial\sigma_{rr}}{\partial \theta}\frac{dr}{2}d\theta\right) + \left(2\frac{\partial\sigma_{rr}}{\partial \theta}\frac{d\theta}{2}dr\cos\frac{d\theta}{2}\right) - \left(2\sigma_{\theta\theta}dr\sin\frac{d\theta}{2}\right) = 0$$

$$(10.5)$$

Dividing through by dr, and noting that for small angles $\sin(d\theta/2) \approx d\theta/2$ and $\cos(d\theta/2) \approx 1$, equation (10.5) reduces to

$$\left(\frac{\partial\sigma_{rr}}{\partial r}rd\theta\right) + \left(\sigma_{rr}d\theta\right) + \left(\frac{\partial\sigma_{rr}}{\partial r}\frac{dr^2}{2}d\theta\right) + \left(\frac{\partial\sigma_{rr}}{\partial\theta}d\theta\right) - \left(2\sigma_{\theta\theta}\frac{d\theta}{2}\right) = 0. \quad (10.5)$$

The third term drops out because dr^2 is tiny relative to the other terms. Dividing this (10.5) through by r d θ yields

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$$\frac{\partial \sigma_{rr}}{\partial r} + \frac{\sigma_{rr}}{r} + \frac{1}{r} \frac{\partial \sigma_{rr}}{\partial \theta} - \frac{\sigma_{\theta\theta}}{r} = 0.$$
(10.6)

This expression is commonly rearranged as (see eq. 5.41 in C&P):

$$\frac{\partial \sigma_{rr}}{\partial r} + \frac{1}{r} \frac{\partial \sigma_{rr}}{\partial \theta} + \frac{\sigma_{rr} - \sigma_{\theta\theta}}{r} = 0.$$
(10.7)

By summing the forces in the θ -direction one can obtain

$$\frac{1}{r}\frac{\partial\sigma_{r\theta}}{\partial\theta} + \frac{\partial\sigma_{r\theta}}{\partial r} + \frac{2\sigma_{r\theta}}{r} = 0.$$
 (10.8)

Equations (10.7) and (10.8) are the equilibrium equations in polar coordinates.

VI Biharmonic equation in polar coordinates

Our starting point is the biharmonic equation

$$\nabla^{4}\phi = \nabla^{2}\nabla^{2}\phi = \left(\frac{\partial^{2}}{\partial x^{2}} + \frac{\partial^{2}}{\partial y^{2}}\right) \left(\frac{\partial^{2}}{\partial x^{2}} + \frac{\partial^{2}}{\partial y^{2}}\right) \phi = 0, \qquad (10.9)$$

and the stresses in terms of the stress function ϕ :

(a)
$$\sigma_{xx} = \frac{\partial^2 \phi}{\partial y^2}$$
, (b) $\sigma_{yy} = \frac{\partial^2 \phi}{\partial x^2}$, (c) $\sigma_{xy} = \frac{-\partial^2 \phi}{\partial x \partial y}$. (10.10)

In order to transform these equations to polar form, we need to know how to express derivatives with respect to x and y in terms of r and θ . We get these relationships from the chain rule:

(a)
$$\frac{\partial \phi}{\partial x} = \frac{\partial \phi}{\partial r} \frac{\partial r}{\partial x} + \frac{\partial \phi}{\partial \theta} \frac{\partial \theta}{\partial x}$$
 (b) $\frac{\partial \phi}{\partial y} = \frac{\partial \phi}{\partial r} \frac{\partial r}{\partial y} + \frac{\partial \phi}{\partial \theta} \frac{\partial \theta}{\partial y}$ (10.11)

We therefore need to know how r and θ relate to x and y.

(a)
$$\theta = \tan^{-1}(y/x)$$
 (b) $r = (x^2 + y^2)^{1/2}$ (10.12)

(a)
$$x = r \cos \theta$$
 (b) $y = r \sin \theta$ (10.13)

Now to the derivatives. Starting with eq. (10.12b)

$$\frac{\partial r}{\partial x} = \frac{1}{2} \left(x^2 + y^2 \right)^{-1/2} \left(2x \right) = \frac{x}{\left(x^2 + y^2 \right)^{1/2}} = \frac{x}{r} = \cos \theta \tag{10.14}$$

$$\frac{\partial r}{\partial y} = \frac{1}{2} \left(x^2 + y^2 \right)^{-1/2} \left(2y \right) = \frac{y}{\left(x^2 + y^2 \right)^{1/2}} = \frac{y}{r} = \sin \theta$$
(10.15)

Now take derivatives of eq. (10.12a). Recalling that $d(\tan^{-1}u) = du/(1+u^2)$

$$\frac{\partial\theta}{\partial x} = \frac{\partial\left(\tan^{-1}(y/x)\right)}{\partial x} = \frac{1}{\left(1 + \left(\frac{y}{x}\right)^2\right)^2} \frac{\partial(y/x)}{\partial x} = \frac{1}{\left(1 + \left(\frac{y}{x}\right)^2\right)^2} \frac{-y}{x^2} = \frac{-y}{r^2} = \frac{-\sin\theta}{r}$$
(10.16)

Similarly

$$\frac{\partial\theta}{\partial y} = \frac{\partial\left(\tan^{-1}(y/x)\right)}{\partial y} = \frac{1}{\left(1 + \left(\frac{y}{x}\right)^2\right)^2} \frac{\partial(y/x)}{\partial y} = \frac{1}{\left(1 + \left(\frac{y}{x}\right)^2\right)^2} \frac{1}{x} \frac{x}{x} = \frac{x}{r^2} = \frac{\cos\theta}{r}$$
(10.17)

Now we can find the derivatives of ϕ in terms of r and θ by substituting eqs. (10.16) and (10.17) into chain rule equations (10.11):

(a)
$$\frac{\partial \phi}{\partial x} = \frac{\partial \phi}{\partial r} \cos \theta - \frac{\partial \phi}{\partial \theta} \frac{\sin \theta}{r}$$
, (b) $\frac{\partial \phi}{\partial y} = \frac{\partial \phi}{\partial r} \sin \theta + \frac{\partial \phi}{\partial \theta} \frac{\cos \theta}{r}$. (10.18)

Second derivatives are found by operating on first derivatives. $(\partial \phi) = (\partial \phi) = (\partial \phi)$

$$\frac{\partial^2 \phi}{\partial x^2} = \frac{\partial \left(\frac{\partial \phi}{\partial x}\right)}{\partial x} = \frac{\partial \left(\frac{\partial \phi}{\partial x}\right)}{\partial r} \cos \theta - \frac{\partial \left(\frac{\partial \phi}{\partial x}\right)}{\partial \phi} \frac{\sin \theta}{r}.$$
 (10.19)

Substituting eq. (10.18a) into eq. (10.19) yields

$$\frac{\partial^2 \phi}{\partial x^2} = \frac{\partial \left(\frac{\partial \phi}{\partial x}\right)}{\partial x} = \frac{\partial \left(\frac{\partial \phi}{\partial r}\cos\theta - \frac{\partial \phi}{\partial \theta}\frac{\sin\theta}{r}\right)}{\partial r}\cos\theta - \frac{\partial \left(\frac{\partial \phi}{\partial r}\cos\theta - \frac{\partial \phi}{\partial \theta}\frac{\sin\theta}{r}\right)}{\partial \theta}\frac{\sin\theta}{r}.$$
(10.20)

This can be expanded as

$$\frac{\partial^2 \phi}{\partial x^2} = \frac{\partial^2 \phi}{\partial r^2} \cos^2 \theta - \frac{\partial^2 \phi}{\partial \theta \partial r} \frac{\sin \theta \cos \theta}{r} + \frac{\partial \phi}{\partial \theta} \frac{\sin \theta \cos \theta}{r^2} - \frac{\partial^2 \phi}{\partial \theta \partial r} \frac{\sin \theta \cos \theta}{r} + \frac{\partial \phi}{\partial r} \frac{\sin^2 \theta}{r} + \frac{\partial^2 \phi}{\partial \theta^2} \frac{\sin^2 \theta}{r^2} + \frac{\partial \phi}{\partial \theta} \frac{\sin \theta \cos \theta}{r^2}$$
(10.21)
The expression for $\frac{\partial^2 \phi}{\partial y^2}$ can be found by the same procedure:

$$\frac{\partial^2 \phi}{\partial y^2} = \frac{\partial^2 \phi}{\partial r^2} \sin^2 \theta + \frac{\partial^2 \phi}{\partial \theta \partial r} \frac{\sin \theta \cos \theta}{r} - \frac{\partial \phi}{\partial \theta} \frac{\sin \theta \cos \theta}{r^2} + \frac{\partial^2 \phi}{\partial \theta \partial r} \frac{\sin \theta \cos \theta}{r} + \frac{\partial \phi}{\partial r} \frac{\cos^2 \theta}{r} + \frac{\partial^2 \phi}{\partial \theta^2} \frac{\cos^2 \theta}{r^2} - \frac{\partial \phi}{\partial \theta} \frac{\sin \theta \cos \theta}{r^2}$$
(10.22)

Equation (10.21) is the expression for σ_{yy} and eq. (10.22) is the expression for σ_{xx} . Notice the term-by-term "symmetry" between these two equations.

These equations can be added to give the expression for $\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2}$.

Recalling that
$$\sin^2\theta + \cos^2\theta = 1$$
, we get

$$\frac{\partial^2\phi}{\partial x^2} + \frac{\partial^2\phi}{\partial y^2} = \frac{\partial^2\phi}{\partial r^2} + \frac{1}{r}\frac{\partial\phi}{\partial r} + \frac{1}{r^2}\frac{\partial^2\phi}{\partial \theta^2} = \nabla^2\phi.$$
(10.23)

The biharmonic equation is obtained by allowing the harmonic equation (10.23) to operate on itself.

$$\nabla^{4}\phi = \nabla^{2}\nabla^{2}\phi = \left(\frac{\partial^{2}}{\partial r^{2}} + \frac{1}{r}\frac{\partial}{\partial r} + \frac{1}{r^{2}}\frac{\partial^{2}}{\partial \theta^{2}}\right)\left(\frac{\partial^{2}}{\partial r^{2}} + \frac{1}{r}\frac{\partial}{\partial r} + \frac{1}{r^{2}}\frac{\partial^{2}}{\partial \theta^{2}}\right)\phi = 0.$$
(10.24)

VIIStresses in polar coordinates

We are now left with the problem of how to determine the stresses in polar coordinates from the stress function ϕ . We know that the mean normal stress (and hence twice the mean stress) is an invariant term - it does not depend on the choice of the system of coordinates. As a result

$$2\sigma_{mean} = \sigma_{xx} + \sigma_{yy} = \sigma_{rr} + \sigma_{\theta\theta} = \left(\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2}\right) = \nabla^2 \phi.$$
(10.25)

By comparing equations (10.23 and 10.25) we know that if one of the terms on the right side of eq. (10.24) equals $\sigma_{\theta\theta}$, then the other terms must sum to equal σ_{rr} . If we can show this for any particular position (r, θ), then the result will hold for all positions. We therefore choose a simple case. Let the r-direction be along the x-axis and the θ -direction be parallel to the y-axis, so $\sigma_{rr} = \sigma_{xx}$ and $\sigma_{\theta\theta} = \sigma_{yy}$. The x-axis corresponds to $\theta = 0^{\circ}$ and the y-direction to $\theta = 90^{\circ}$. So

$$\frac{\partial^2 \phi}{\partial x^2} = \sigma_{yy} = \sigma_{\theta\theta} = \frac{\frac{\partial^2 \phi}{\partial r^2} \cos^2 \theta - \frac{\partial^2 \phi}{\partial \theta \partial r} \frac{\sin \theta \cos \theta}{r} + \frac{\partial \phi}{\partial \theta} \frac{\sin \theta \cos \theta}{r^2}}{-\frac{\partial^2 \phi}{\partial \theta \partial r} \frac{\sin \theta \cos \theta}{r} + \frac{\partial \phi}{\partial r} \frac{\sin^2 \theta}{r} + \frac{\partial^2 \phi}{\partial \theta^2} \frac{\sin^2 \theta}{r^2} + \frac{\partial \phi}{\partial \theta} \frac{\sin \theta \cos \theta}{r^2}}{(10.26)}$$

For our case of $\theta = 0^{\circ}$, all terms with $\sin \theta$ are zero and this simplifies to $\sigma_{\theta\theta} = \frac{\partial^2 \phi}{\partial r^2}$ (10.27)

Similarly

$$\frac{\partial^2 \phi}{\partial y^2} = \sigma_{xx} = \sigma_{rr} = \frac{\frac{\partial^2 \phi}{\partial r^2} \sin^2 \theta + \frac{\partial^2 \phi}{\partial \theta \partial r} \frac{\sin \theta \cos \theta}{r} - \frac{\partial \phi}{\partial \theta} \frac{\sin \theta \cos \theta}{r^2}}{r^2} + \frac{\frac{\partial^2 \phi}{\partial \theta \partial r} \frac{\sin \theta \cos \theta}{r} + \frac{\partial \phi}{\partial r} \frac{\cos^2 \theta}{r} + \frac{\partial^2 \phi}{\partial \theta^2} \frac{\cos^2 \theta}{r^2} - \frac{\partial \phi}{\partial \theta} \frac{\sin \theta \cos \theta}{r^2}}{r^2}}{(10.28)}$$

Again $\theta = 0^{\circ}$, so all terms with $\sin \theta$ are zero, and this simplifies to $\sigma_{rr} = \frac{1}{r} \frac{\partial \phi}{\partial r} + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \theta^2}.$ (10.29)

Note that $\sigma_{\theta\theta} + \sigma_{rr}$ does indeed equal $\nabla^2 \phi = \frac{\partial^2 \phi}{\partial r^2} + \frac{1}{r} \frac{\partial \phi}{\partial r} + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \theta^2}$.

The shear stress $\theta_{r\theta}$ can be determined from σ_{xy} and is given by

(a)
$$\sigma_{r\theta} = \frac{-\partial}{\partial r} \left(\frac{1}{r} \frac{\partial \phi}{\partial \theta} \right)$$
 or $\sigma_{r\theta} = \frac{-1}{r} \frac{\partial^2 \phi}{\partial r \partial \theta} + \frac{1}{r^2} \frac{\partial \phi}{\partial \theta}$. (10.30)

Stresses in Polar Coordinates





