

RHEOLOGY & LINEAR ELASTICITY

I Main Topics

- A Rheology: Macroscopic deformation behavior
- B Importance of fluids and fractures in deformation
- C Linear elasticity for homogeneous isotropic materials

II Rheology: Macroscopic deformation behavior

A Elasticity

- 1 Deformation is reversible when load is removed
- 2 Stress (σ) is related to strain (ϵ)
- 3 Deformation **is not** time dependent if load is constant
- 4 Examples: Seismic (acoustic) waves, rubber ball

D Viscosity

- 1 Deformation is irreversible when load is removed
- 2 Stress (σ) is related to strain **rate** ($\dot{\epsilon}$)
- 3 Deformation **is** time dependent if load is constant
- 4 Examples: Lava flows, corn syrup

C Plasticity

- 1 No deformation until yield strength is **locally** exceeded; then irreversible deformation occurs under a constant load
- 2 Stress is related to strain
- 3 Deformation can increase with time under a constant load
- 4 Examples: plastics, soils

D Other rheologies

- 1 Elastoplastic and viscoplastic (e.g., paint) rheologies
- 2 Power-law creep $\{\dot{\epsilon} = (\sigma_1 - \sigma_3)^n \exp(-Q/RT)\}$ (e.g., rock salt)

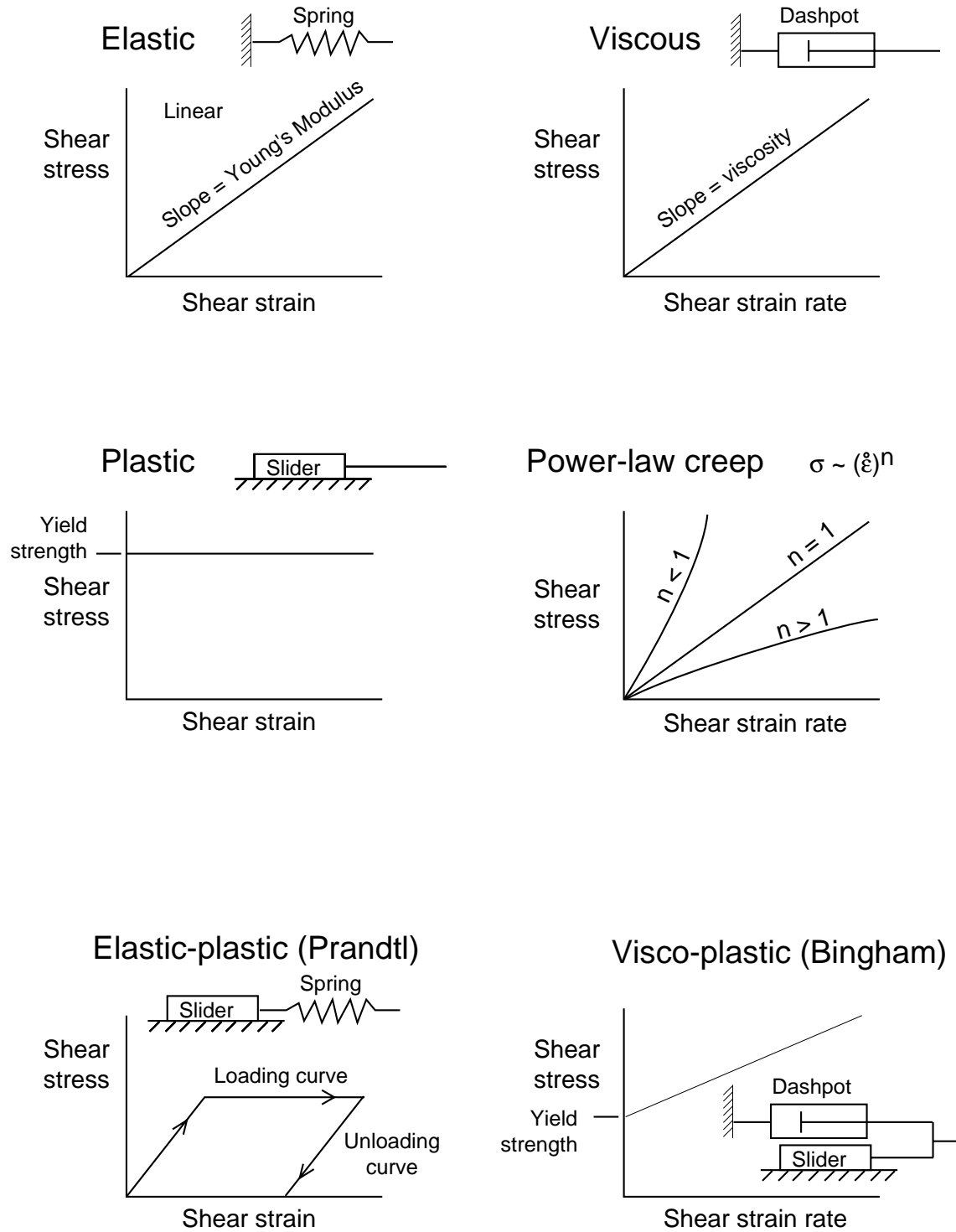
E Linear vs. nonlinear behavior

F Rheology = $\mathbf{f}(\sigma_{ij}, \text{fluid pressure}, \dot{\epsilon}, \text{chemistry}, \text{temperature})$

G Rheologic equation of real rocks = ?

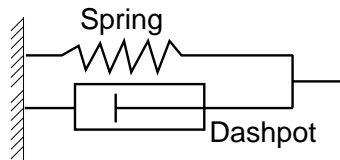
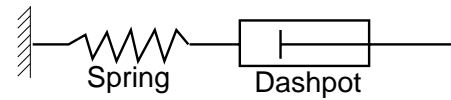
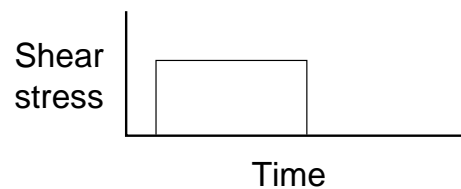
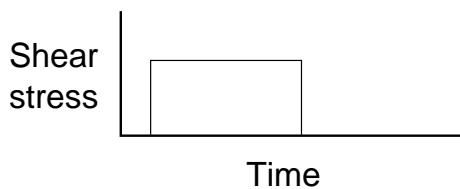
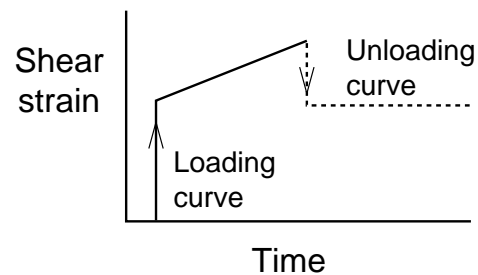
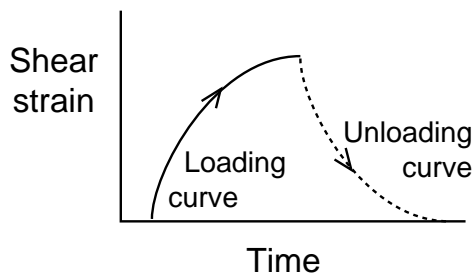
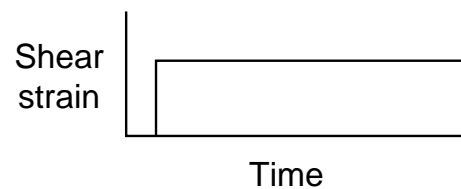
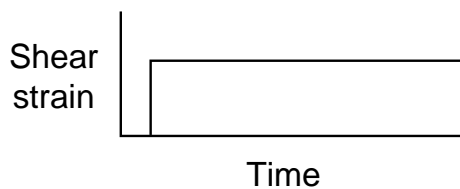
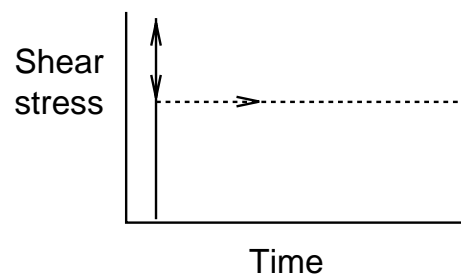
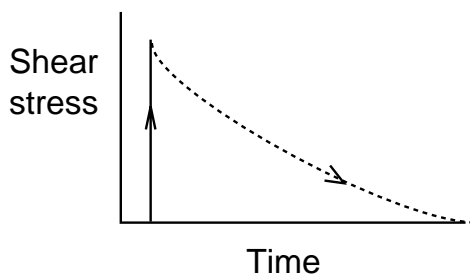
Common Rheologic Models (Displacements & forces below anaolous to strain & stress)

Fig. 20.1



Common Visco-elastic Rheologic Models
(Displacements & forces below analogous to strain & stress)
From Fung, 1977

Fig. 20.2

Visco-elastic (Kelvin)**Visco-elastic (Maxwell)****Creep functions in response to step loads in stress****Relaxation functions under constant strain**

III Importance of fluids and fractures in deformation

A Observed effects of water on rocks

- 1 Lowers long term strength
- 2 Dissolves/precipitates minerals
- 3 Increases reaction rates by orders of magnitude

B Evidence for fluid-assisted mass/volume change in deformed rocks

- 1 Martinsburg shale: "pressure solution" considered responsible for 50% volume loss based on strain recorded by fossils.
- 2 Profound implications for "balanced cross sections" which are constructed assuming conservation of volume of deformed rock
- 3 Effect of cracks on "pressure solution": cracks greatly enhance the area of a rock mass that can be exposed to fluids

C Effect of cracks on fluid flow

- 1 Limited influence where fractures are not interconnected
- 2 Can increase flow rates by several orders of magnitude where fractures are connected

D Veins provide evidence for episodic fluid flow and fracturing

IV Linear elastic stress-strain relationships

A Force and displacement of a spring (from Hooke, 1676)

- 1 $F = kx$: F = force, k = spring constant, x = displacement
- 2 *Elastic potential energy* $= \int_0^x F dx = \int_0^x kx dx = k \int_0^x x dx = \frac{1}{2} kx^2$

Equation 1 can be recast in terms of stress and strain:

$$3 \quad \sigma_{11}A = k \int_0^L \epsilon_{11} dx$$

where $\epsilon_{11} = du/dx$, A = x-section area, and L = spring length

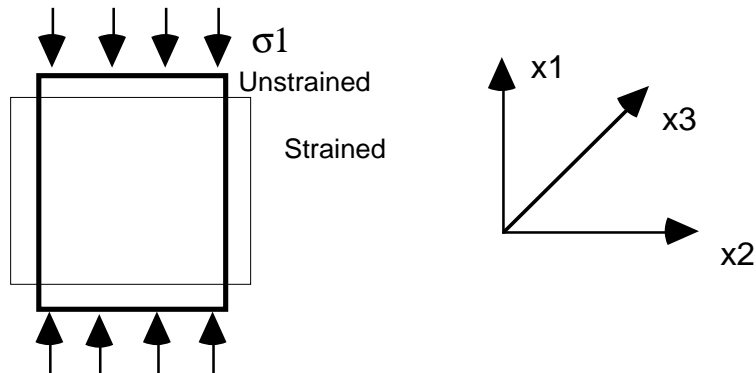
If ϵ_{11} is a constant along the length of the spring, then

$$4 \quad \sigma_{11}A = k\epsilon_{11} \int_0^L dx = k\epsilon_{11}L$$

$$5 \quad \sigma_{11} = \frac{kL}{A} \epsilon_{11}; \text{ stress:strain relationship is linear. OK for small strains.}$$

B Linear elasticity

- 1 Constitutive laws for relating stress and (infinitesimal) strain
- 2 Uniaxial stress: $\sigma_{11} = \sigma_1 \neq 0; \sigma_{22} = \sigma_{33} = 0$



a $\epsilon_{11} = \sigma_{11}/E$ Hooke's Law (or $\epsilon_1 = \sigma_1/E$)

E = Young's modulus; dimensions of stress

b $\epsilon_{22} = \epsilon_{33} = -\nu \epsilon_{11}$ (or $\epsilon_2 = \epsilon_3 = -\nu \epsilon_1$)

i ν = Poisson's ratio; dimensionless

ii Strain in one direction tends to induce strain in another

- 3 Linear elasticity in 3 dimensions

From superposition of Hooke's Law for homogeneous isotropic materials

a $\epsilon_{11} = \sigma_{11}/E - (\sigma_{22} + \sigma_{33})(\nu/E)$

b $\epsilon_{22} = \sigma_{22}/E - (\sigma_{11} + \sigma_{33})(\nu/E)$

c $\epsilon_{33} = \sigma_{33}/E - (\sigma_{11} + \sigma_{22})(\nu/E)$

d Directions of principal stresses and principal strains coincide

e Extension in one direction can occur without tension

f Compression in one direction can occur without shortening

D Isotropic (hydrostatic) stress: $\sigma_1 = \sigma_2 = \sigma_3$; no shear stress

E Uniaxial strain: $\epsilon_{11} = \epsilon_1 \neq 0; \epsilon_{22} = \epsilon_{33} = 0$

F Plane stress: $\sigma_{33} = \sigma_3 = 0; \sigma_{11} \neq 0; \sigma_{22} \neq 0$

Thin plate approximation; stress perpendicular to plane are zero

G Plane strain: $\epsilon_{33} = \epsilon_3 = 0; \epsilon_{11} \neq 0; \epsilon_{22} \neq 0$

1 Displacement in the 3-direction is constant (zero)

2 Plate is confined between rigid walls \perp to x_3

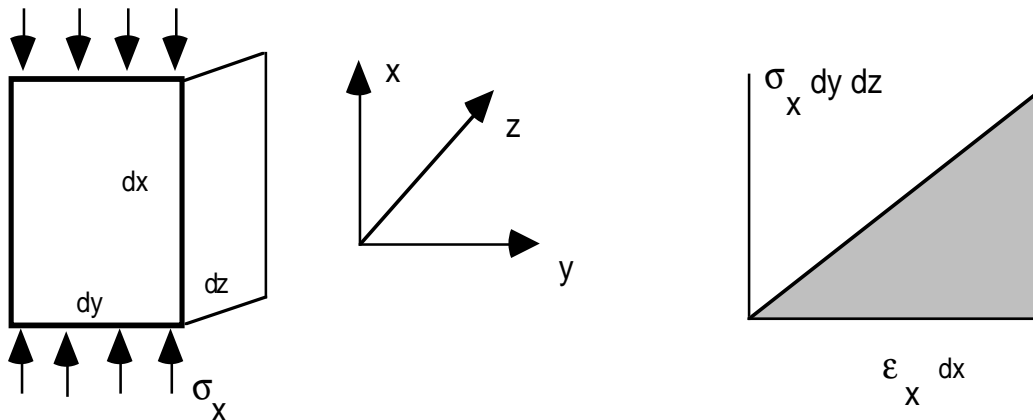
3 Thick plate approximation

H Pure shear stress: $\sigma_1 = -\sigma_2; \sigma_3 = 0$

IV Strain energy

A $W = (F)(u) = E$

B Uniaxial stress



1 $dW = (F)(du) = 1/2 (\sigma_x dy dz) (\epsilon_x dx) = 1/2 (\sigma_x \epsilon_x) (dx dy dz)$

2 Strain energy density = $W_0 = dW/(dx dy dz) = 1/2 (\sigma_x \epsilon_x)$

C Strain energy associated with three-dimensional loading
(in terms of principal stresses and principal strains)

1 $dW = 1/2 (\sigma_1 \epsilon_1 + \sigma_2 \epsilon_2 + \sigma_3 \epsilon_3) (dx dy dz)$

2 $W_0 = dW/(dx dy dz) = 1/2 (\sigma_1 \epsilon_1 + \sigma_2 \epsilon_2 + \sigma_3 \epsilon_3)$

V Relationships among different elastic moduli

1 $G = \mu = \text{shear modulus} = E/(2[1+\nu]);$

$\epsilon_{xy} = \sigma_{xy}/2G$

2 $\lambda = \text{Lame' constant} = E\nu/([1 + \nu][1 - 2\nu])$

3 $K = \text{bulk modulus} = E/(3[1 - 2\nu])$

4 $\beta = \text{compressibility} = 1/K$

$\Delta = \epsilon_{xx} + \epsilon_{yy} + \epsilon_{zz} = -p/K; p = \text{pressure}$

5 P-wave speed: $V_p = \sqrt{\left(K + \frac{4}{3}\mu\right) / \rho}$

6 S-wave speed: $V_s = \sqrt{\mu / \rho}$

Additional References

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