

## 14. Folds

### I Main Topics

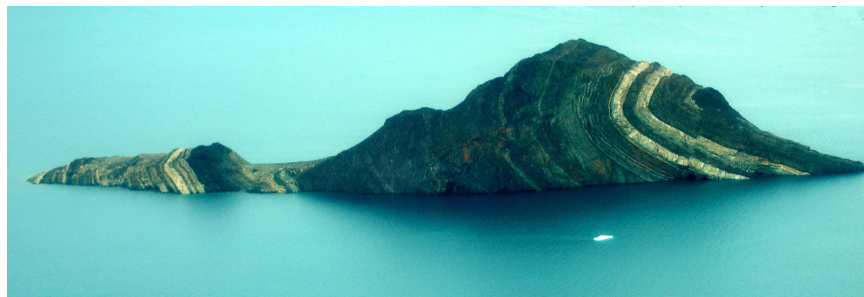
- A Local geometry of a plane curve (cylindrical fold)
- B Local geometry of a curved surface (3D fold)
- C Numerical evaluation of curvature (geometry)
- D Kinematics of folding
- E Fold terminology and classification (geometry)

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[http://upload.wikimedia.org/wikipedia/commons/a/ae/Caledonian\\_orogeny\\_fold\\_in\\_King\\_Oscar\\_Fjord.jpg](http://upload.wikimedia.org/wikipedia/commons/a/ae/Caledonian_orogeny_fold_in_King_Oscar_Fjord.jpg)

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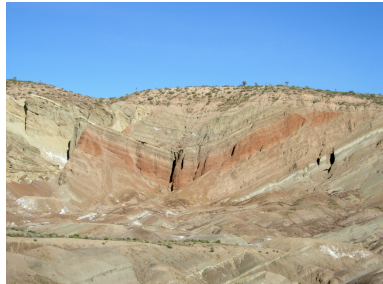
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Anticline, New Jersey



[http://en.wikipedia.org/wiki/File:NJ\\_Route\\_23\\_antiline.jpg](http://en.wikipedia.org/wiki/File:NJ_Route_23_antiline.jpg)

Syncline, Rainbow Basin, California



[http://en.wikipedia.org/wiki/File:Rainbow\\_Basin.JPG](http://en.wikipedia.org/wiki/File:Rainbow_Basin.JPG)

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Folds, New South Wales, Australia



[http://en.wikipedia.org/wiki/File:Folded\\_Rock.jpg](http://en.wikipedia.org/wiki/File:Folded_Rock.jpg)

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Folds in granite, Sierra Nevada, California

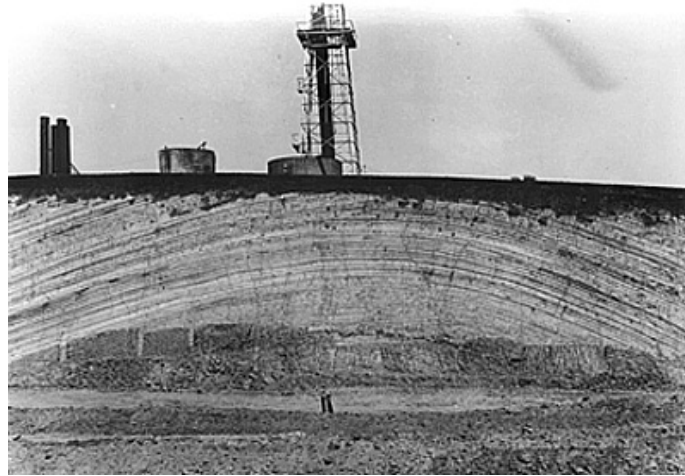


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Energy Resources and an Anticline



<http://www.wou.edu/las/physci/Energy/graphics/OilAnticline.jpg>

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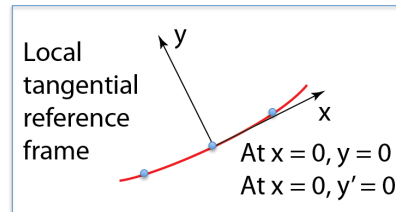
II Local geometry of a plane curve (cylindrical fold) in a tangential reference frame

A Express the plane curve as a power series:

$$1 \quad y = [\dots + C_{-2}x^{-2} + C_{-1}x^{-1}] + [C_0x^0] + [C_1x^1 + C_2x^2 + C_3x^3 + \dots]$$

At  $x = 0$ ,  $y = 0$ , so all the coefficients for terms with non-positive exponents must be zero

$$2 \quad y = C_1x^1 + C_2x^2 + C_3x^3 + \dots$$



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### II Local geometry of a plane curve (cylindrical fold) in a tangential reference frame

$$2 \quad y = C_1 x^1 + C_2 x^2 + C_3 x^3 + \dots$$

Now examine  $y'$

$$3 \quad y' = C_1 x^0 + 2C_2 x^1 + 3C_3 x^2 + \dots = 0$$

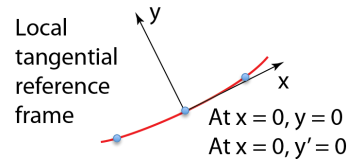
At  $x = 0$ ,  $y' = 0$ , so  $C_1 = 0$ , so

$$4 \quad y = C_2 x^2 + C_3 x^3 + \dots = 0$$

As  $x \rightarrow 0$ , higher-order terms vanish

$$5 \quad \lim_{x \rightarrow 0} y = C_2 x^2$$

$$6 \quad \lim_{x \rightarrow 0} k = |y(s)''| = |y(x)''| = 2C_2$$



So all plane curves are locally second-order (parabolic).

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### III Local geometry of a curved surface in a tangential reference frame

A Plane curves are formed by intersecting a curved surface with a plane containing the surface normal

B These plane curves  $z = z(x, y)$  are locally all of second-order, so any continuous surface is locally 2nd order. The general form of such a surface in a tangential frame is

$$z = Ax^2 + Bxy + Cy^2$$

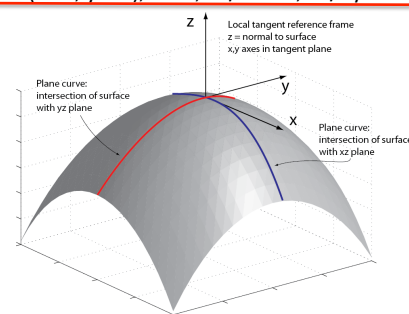
This is the equation of a paraboloid: all surfaces are locally either elliptic or hyperbolic paraboloids

C Example: curve (normal section) in the arbitrary plane  $y = mx$

$$y = \lim_{x \rightarrow 0, y \rightarrow 0} z = Ax^2 + Bx(mx) + C(mx)^2 = (A + Bm + Cm^2)x^2$$

Sum of constants

$$\text{At } (x=0, y=0), z=0, \partial z / \partial x = 0, \partial z / \partial y = 0$$



Parabolic plane curves

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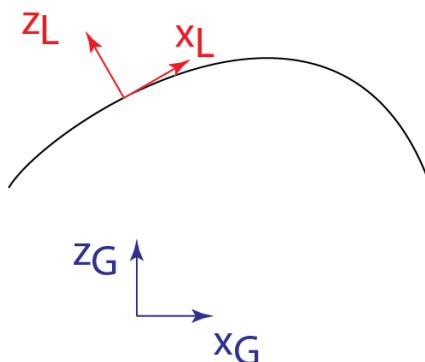
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### III Local geometry of a curved surface ... (cont.)

#### D Dilemma

- 1 Evaluating curvatures of a surface  $z_L = z_L(x_L, y_L)$ , where " $z_L$ " is normal to the surface, is easy
- 2 The "global" reference frame,  $z_G = z_G(x_G, y_G)$ , in which data are collected are usually misaligned with the tangential local reference frame
- 3 Alignment is generally difficult



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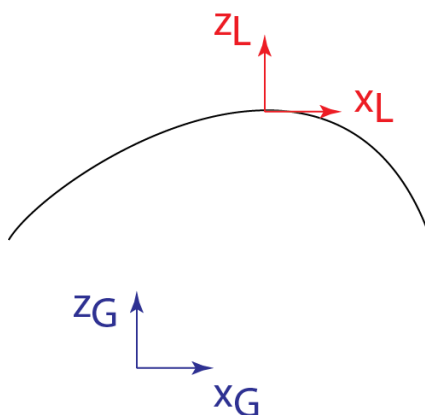
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### III Local geometry of a curved surface ... (cont.)

#### E "resolution"

- 1 At certain places the local and global reference frames are easily aligned though: at the summits or bottoms of folds
- 2 We will evaluate the curvatures there, leaving the more general problem to "later"



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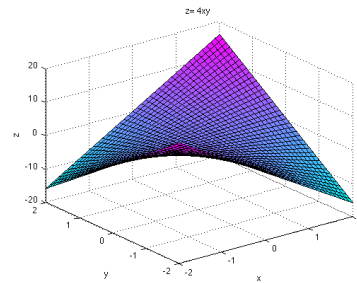
### III Local geometry of a curved surface ... (cont.)

#### F Example (analytical)

$$z_G = 4x_G y_G$$

1 First plot and evaluate  $z_G$  near (0,0)

```
>> [X,Y] = meshgrid([-2:0.1:2]);
>> Z=4*X.*Y;
>> surf(X,Y,Z);
>> xlabel('x'); ylabel('y');
>> zlabel('z'); title('z= 4xy')
```



This is a saddle

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#### F Example (analytical) (cont.)

$$z_G = 4x_G y_G$$

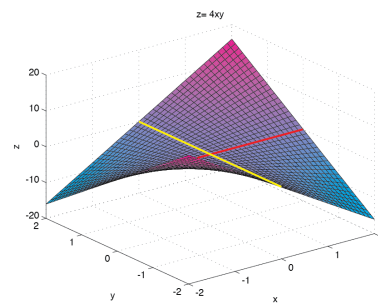
2 Now evaluate the first derivatives

a  $\partial z_G / \partial x_G = 4y_G$

b  $\partial z_G / \partial y_G = 4x_G$

c Both derivatives equal zero at (0,0)

3 The local tangential and global reference frames are aligned at (0,0)



```
>> hold on
>> plot3(X(21,:),Y(21,:),Z(21:),'r')
>> plot3(X(:,21),Y(:,21),Z(:,21),'y')
```

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F Example (analytical)  
(cont.)

$$z_G = 4x_G y_G$$

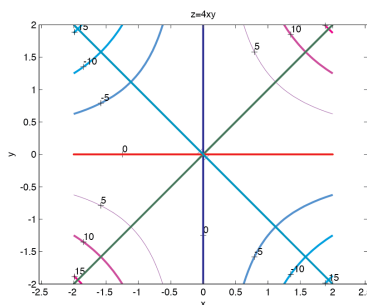
4 Now evaluate the  
second derivatives

a  $\partial^2 z_G / \partial x_G^2 = 0$

b  $\partial^2 z_G / \partial x_G \partial y_G = 4$

c  $\partial^2 z_G / \partial y_G \partial x_G = 4$

d  $\partial^2 z_G / \partial y_G^2 = 0$



```
>> c=contour(X,Y,Z); clabel(c);
>> xlabel('x'); ylabel('y');
>> title('z=4xy')
>> hold on
>> plot([0 0],[-2 2],[-2 2],[-2 2],[0 0],[-2 2],[2 -2])
>> axis equal
```

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F Example (analytical) (cont.)

$$z_G = 4x_G y_G$$

5 Now form the Hessian matrix

$$H = \begin{bmatrix} \partial^2 z / \partial x^2 & \partial^2 z / \partial x \partial y \\ \partial^2 z / \partial y \partial x & \partial^2 z / \partial y^2 \end{bmatrix} = \begin{bmatrix} 0 & 4 \\ 4 & 0 \end{bmatrix}$$

6 Find its eigenvectors and  
eigenvalues

```
>> H=[0 4;4 0]
```

H =

0 -4

-4 0

```
>> [v,k]=eig(H)
```

v =

-0.7071 0.7071

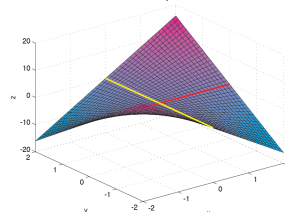
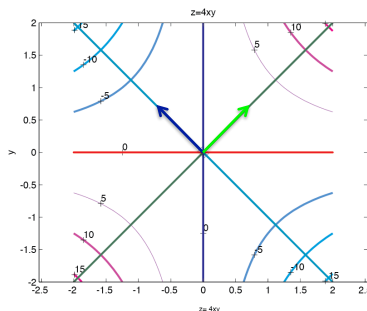
0.7071 0.7071

k =

-4 0

0 4

Saddle  
geometry much  
more clear in  
principal  
reference frame



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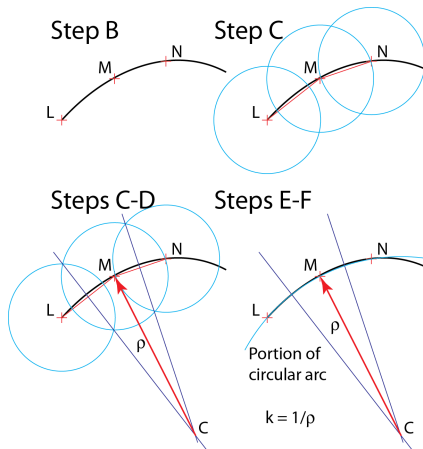
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### IV Evaluation of curvature from discrete data (geometry)

- A Three (non-colinear) points define a plane – and a circle.
- B Locate three discrete non-colinear points along a curve (e.g., L, M, N)
- C Draw the perpendicular bisectors to line segments LM and MN
- D Intersect perpendicular bisectors at the center of curvature C.
- E The radius of curvature ( $\rho$ ) equals the distance from C to L, M, or N.
- F The curvature is reciprocal of the radius of curvature ( $k = 1/\rho$ )
- G Local geometry of a curve also is circular!



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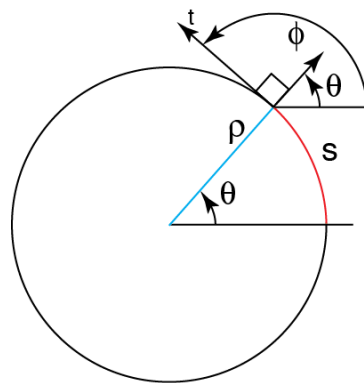
### IV Kinematics of folding (strain)

- A Curvature of a plane curve  
 $k = d\phi/ds$ , where  
 $\phi$  = orientation of tangent  $\mathbf{t}$  to curve  
 $s$  = distance along curve
- B Curvature of a circular arc  
 $\phi = \theta + 90^\circ$ , so  $d\phi = d\theta$   
 $s = \rho\theta$ , so  $ds = \rho d\theta$   
 $k = d\phi/ds = d\theta/ds = 1/\rho$

Large curvature = small radius  
 Small curvature = large radius

- C Curvature can be assigned a sign

+ = concave up  
 - = concave down



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### V Kinematics of folding (cont.)

#### D Layer-parallel normal strain ( $\epsilon_{\theta\theta}$ ) for cylindrical folds

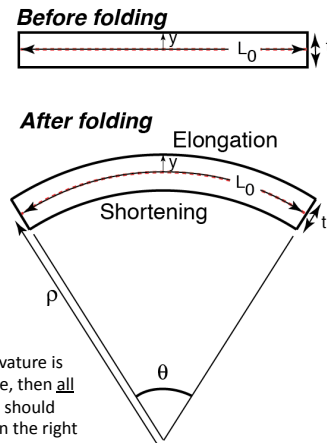
- 1 Mid-plane of layer ( $y = 0$ ) maintains length  $L_0$
- 2 Layer maintains thickness  $t$  during folding

$$\epsilon_{\theta\theta} = \frac{\Delta L}{L_0} = \frac{L_1 - L_0}{L_0} = \frac{(\rho + y)\theta - \rho\theta}{\rho\theta} = \frac{y}{\rho} = yk$$

$$\epsilon_{\theta\theta} \left( y = \frac{t}{2} \right) = \frac{+tk}{2} \text{ (elongation)}$$

$$\epsilon_{\theta\theta} \left( y = -\frac{t}{2} \right) = \frac{-tk}{2} \text{ (contraction)}$$

Note: If convex curvature is considered negative, then all the equations here should have minus signs on the right side



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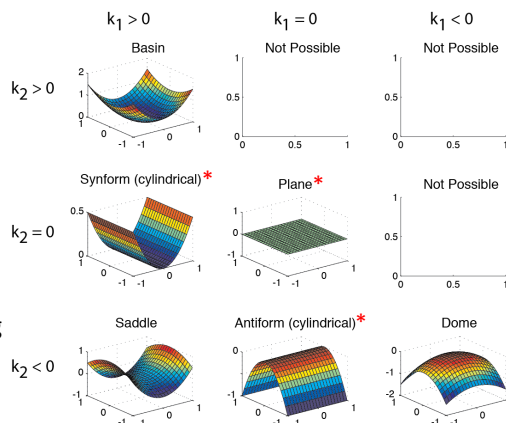
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### V Kinematics of folding (cont.)

#### E Layer-parallel normal strain for three-dimensional folds

- 1 Gauss' Theorem: If the *product* of the principal curvatures (i.e., the Gaussian curvature  $K = k_1 k_2$ ) is constant, then a deformed *surface* remains unstrained\*
- 2 For geologic folds, the Gaussian curvature invariably changes during folding, so layer-parallel strains will occur on the surfaces, as well as interiors, of folded layers



Curvature-based classification scheme for 3D folds

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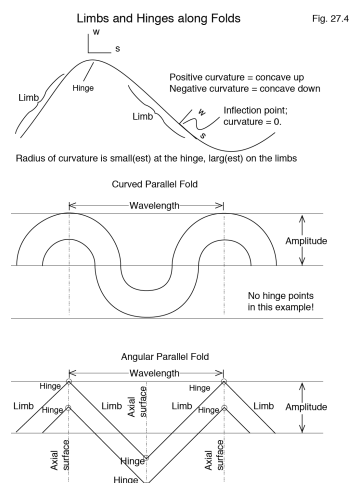
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### VI Fold terminology and classification

- A **Hinge point**: point of local maximum curvature.
- B **Hinge line**: connects hinge points along a given layer.
- C **Axial surface**: locus of hinge points in **all** the folded layers.
- D **Limb**: surface of low curvature.



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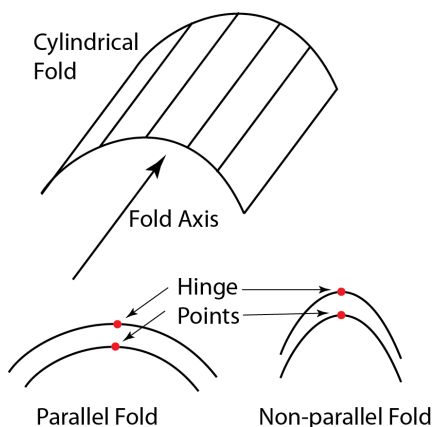
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## 14. Folds

### VI Fold terminology and classification (cont.)

- D **Cylindrical fold**: a surface swept out by moving a straight line parallel to itself
  - 1 **Fold axis**: line that can generate a cylindrical fold
  - 2 **Parallel fold**: top and bottom of layers are parallel and layer thickness is preserved\*
  - 3 **Non-parallel fold**: top and bottom of layers are not parallel; layer thickness is not preserved\*
- \* **Assumption**: bottom and top of layer were originally parallel



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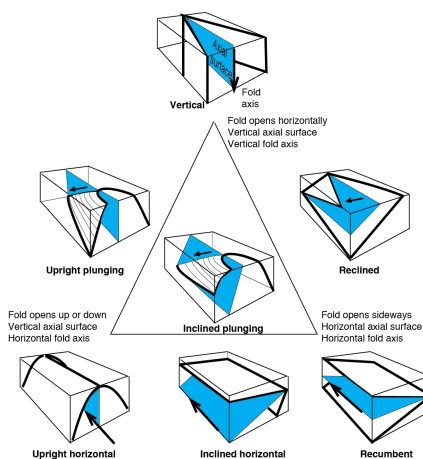
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### VI Fold terminology and classification (cont.)

#### E Fleuty's Classification

- 1 Based on orientation of axial surface and fold axis
- 2 First modifier (e.g., "upright") describes orientation of axial surface
- 3 Second modifier (e.g., "horizontal") describes orientation of fold axis



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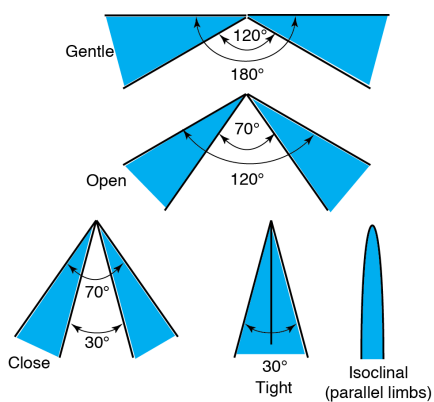
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### Fold terminology and classification (cont.)

#### F Inter-limb angle

Interlimb angle	Classification
180° - 120°	Gentle
120° - 70°	Open
70° - 30°	Close
30° - 0°	Tight
"0°"	Isoclinal
Negative	Mushroom



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