ORE 330 Mineral and Energy Resources of the Sea

Mining Technology

Deep-Sea Mining Systems

- A. Manganese Nodule Systems
 - 1. Tested systems
 - a) Robotic Miners

Design parameters

Pick-up systems

Airlift systems

- b) Continuous Line Bucket
- 2. Untested systems
 - a) Submersible Shuttle System

B. Manganese Crust Mining System

Design Parameters

Crust thickness problem

Cutter depth optimization

Ripper design – fragmentation criteria

Air lift design

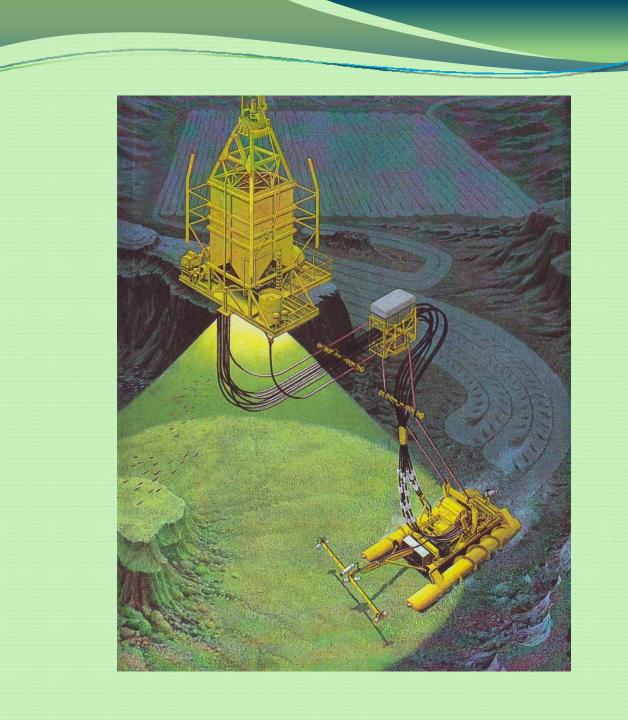
C. In-Situ Leach Mining Systems

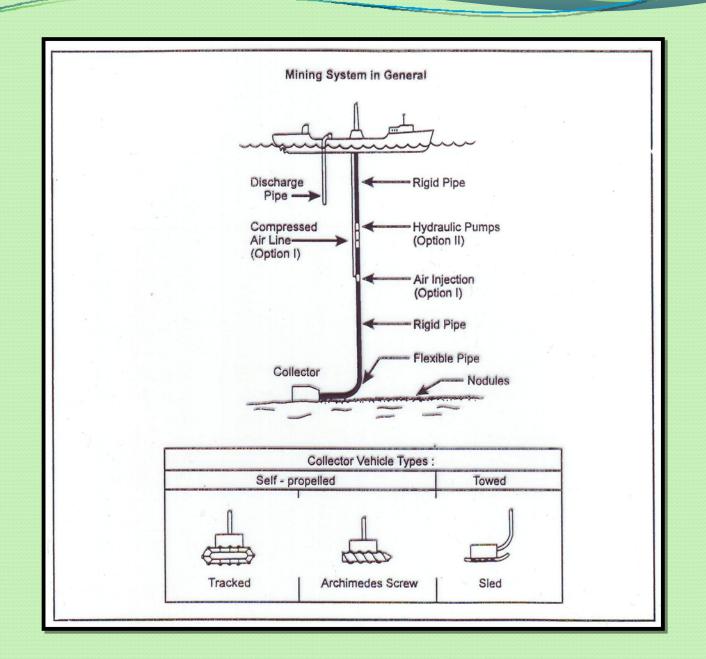
Operations for manganese crust and harbor sediment cleanup

Single point mooring systems for leach mining

Adaptation for biomining

D. Polymetallic Sulfide Mining Systems Concepts





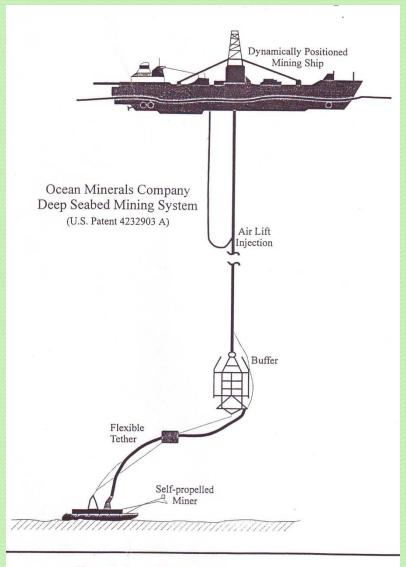


Figure 2. Complexity of design of hydraulic system.

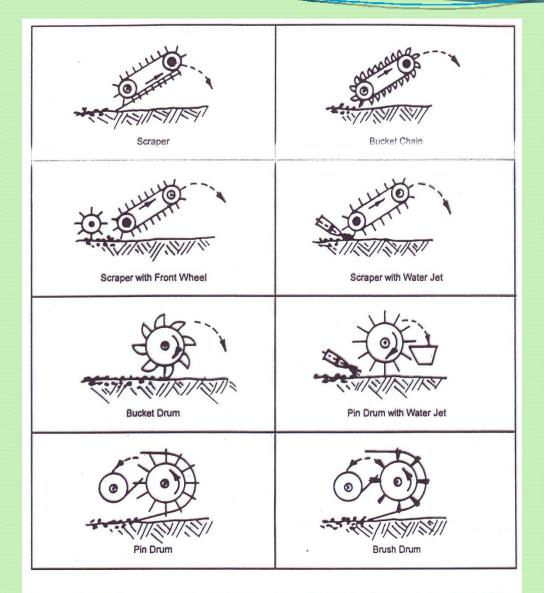
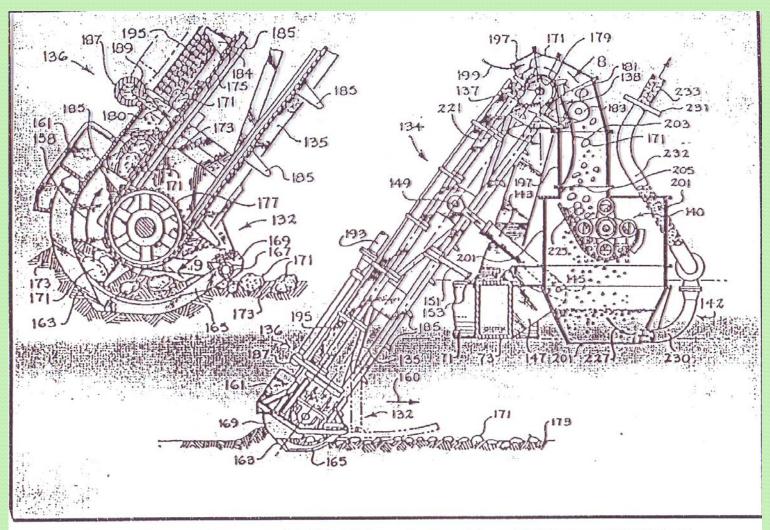
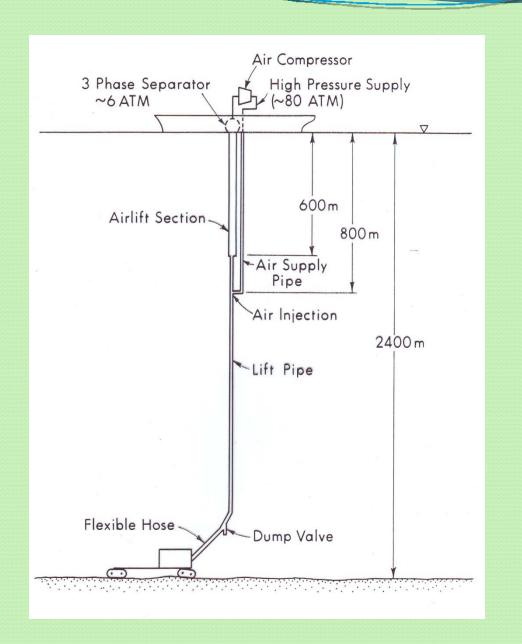


Figure 2.1.4 Various nodule pick-up principles. (from Thiel et al. 1991 redrawn from Bath 1989)



Ocean Minerals Company Nodule Pick-up System (from U.S. Patent 4232903 A)



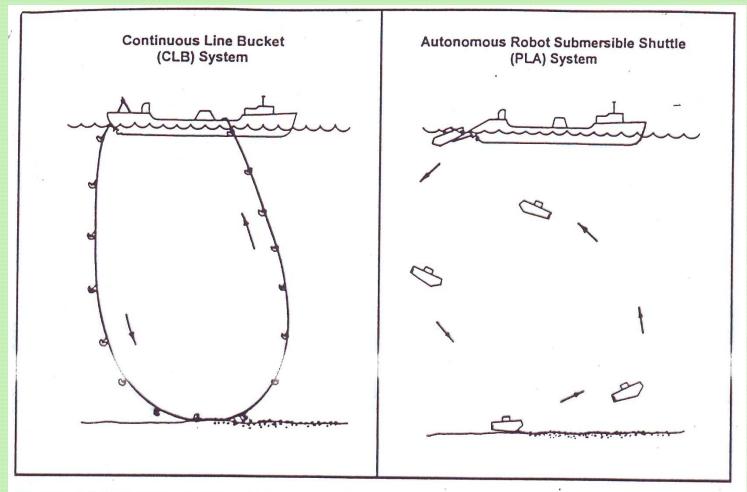
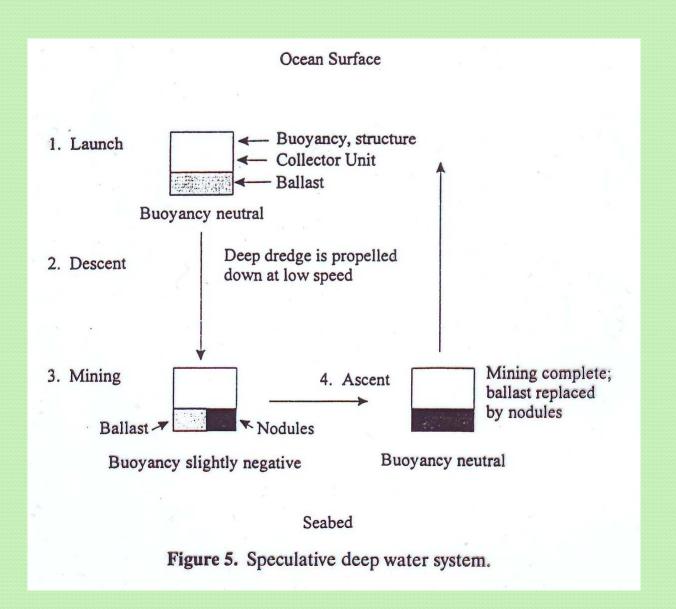
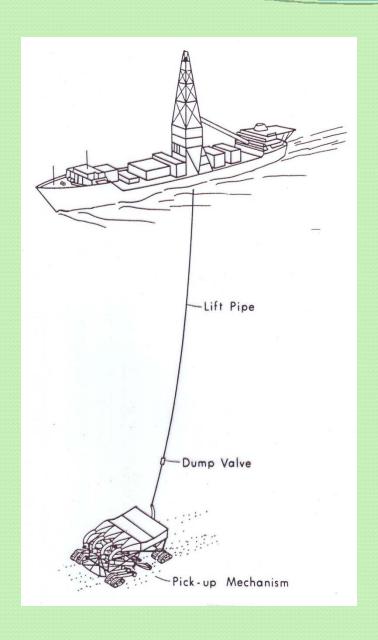
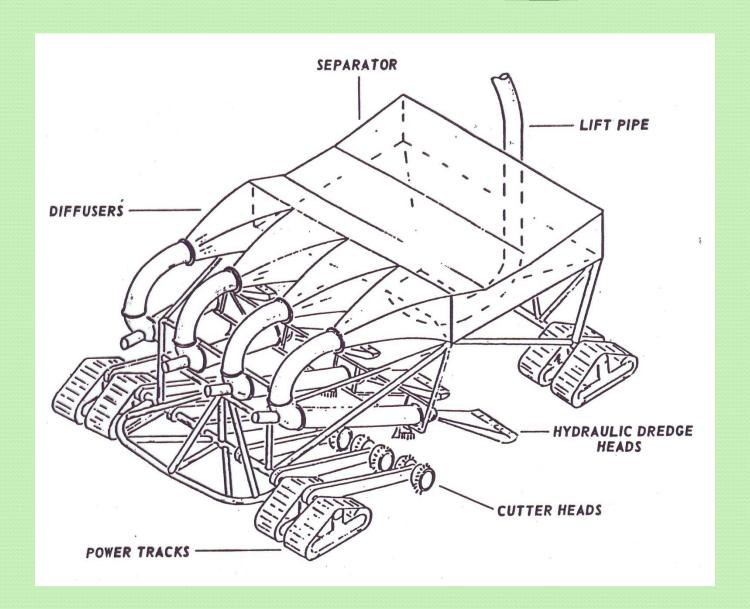


Figure 2.1.2 Continuous Line Bucket (CLB) mining system and the Preleveur Libre Autonome (PLA) or autonomous robot submersible shuttle system. (not to scale) (from Thiel et al. 1991)







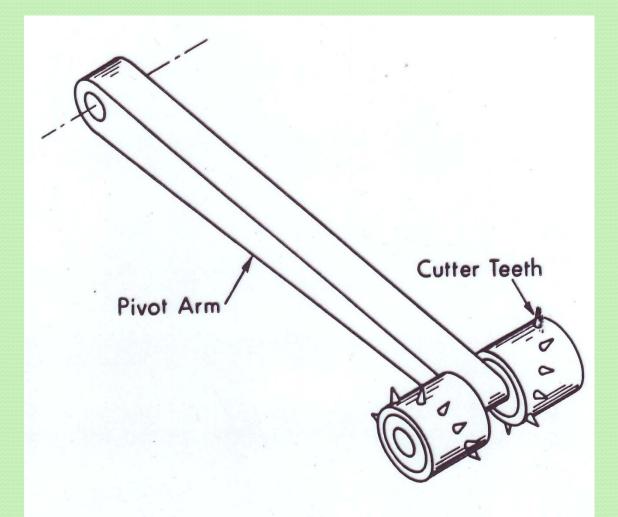


Figure 3. Cutter head design for manganese crust miner (after Halkyard 1985).

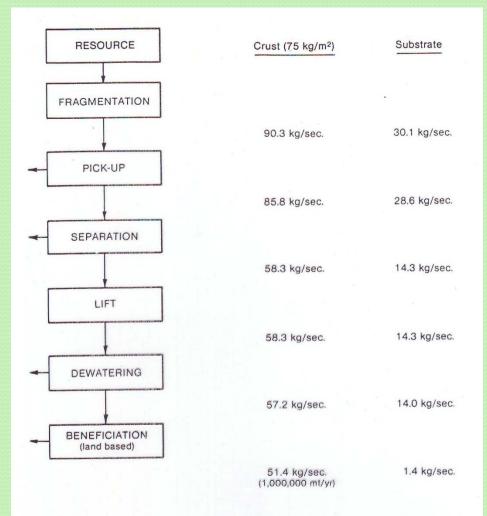
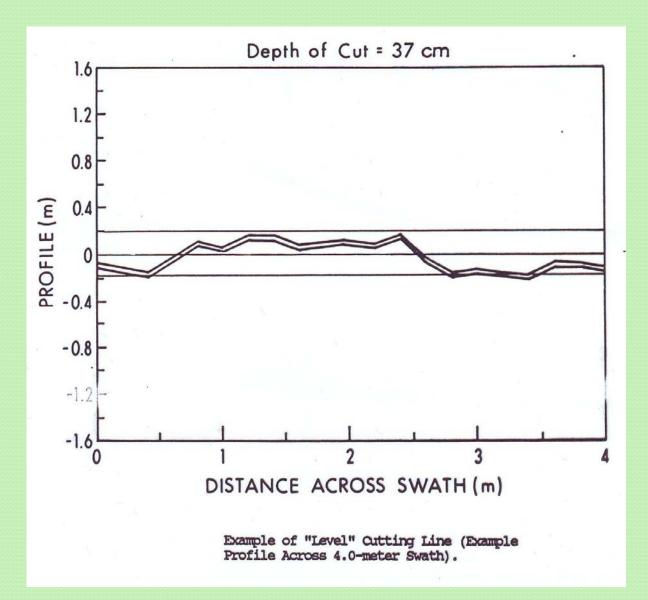
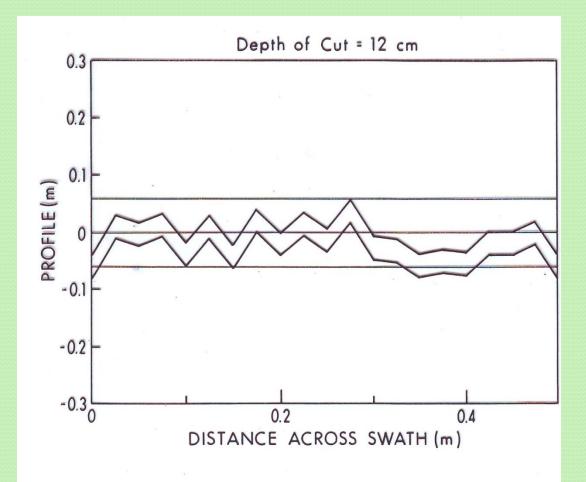


Figure 4-4. Base-case material flows (wet weight)

BASE-CASE MINING PARAMETERS (25% Substrate in Recovered Ore)

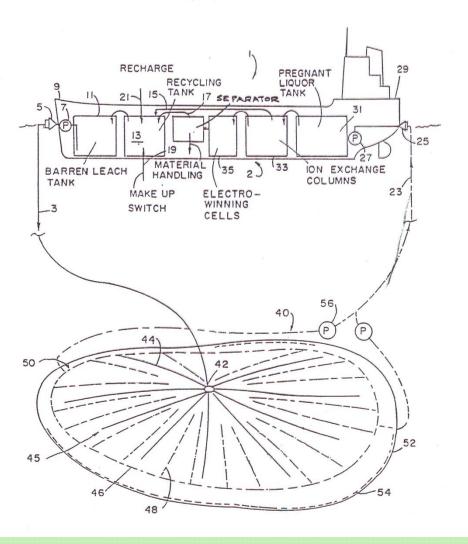
Operation	Recovery Efficiency (%
Crust Fragmentation	cs
Pickup Crusts	95
Pickup Substrate Separation @ 0.25 m/s	95
Crust Recovery	6.3
Substrate Shipboard Dewatering	52
Crust	93
Substrate	93
Beneficiation	
Crust	90
Substrate	10





Example of "Level" Cutting Line (Example Profile across 0.5-meter Swath).

FIG. I

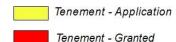


Nautilus Minerals' Tenements



SOUTHWEST PACIFIC REGION LOCATION OF TENEMENTS

May 2008 © Nautilus Minerals



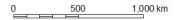
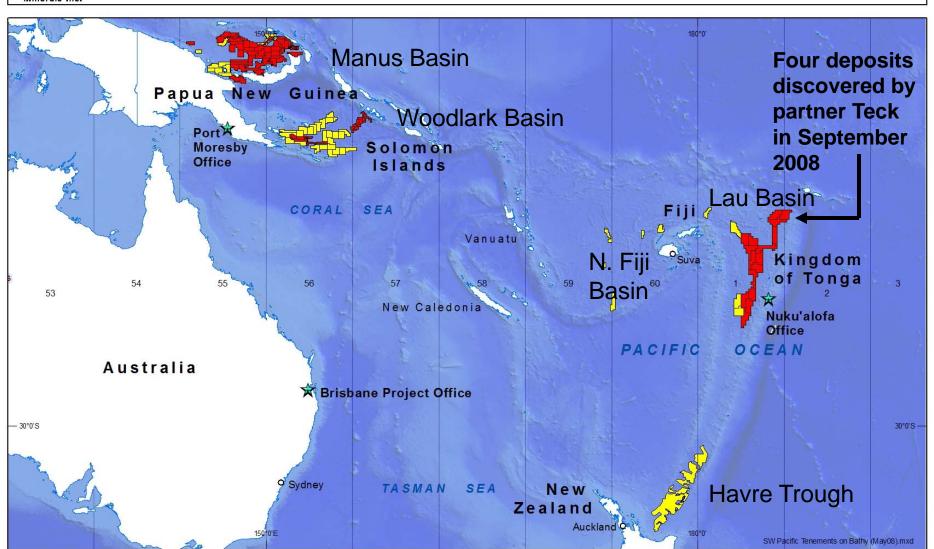


Plate Carree Projection. WGS84 Datum.



Mining system to be deployed by Nautilus Minerals





Technip (Houston) to build RALS using offshore oil technology and Soil Machine Dynamics (UK) to build two 6000 peak tpd SMTs Mining to start in 2013 subject to timely permitting by PNG

Extracting Value - Seafloor Mining Tools (SMTs)



- Soil Machine Dynamics (UK) contract to design and build
 - Experts in deep sea ROV and trenching machine design
 - US\$84 million contract for three specialized mining machines
 - Includes control systems and associated umbilicals, handling, and deck equipment
- Engineering has been underway for over two years
- Contract suspension released in March 2009

Auxiliary Miner- cuts ore on uneven surfaces; benching the site



Bulk Miner- cuts ore at high rates on areas benched by Auxiliary Miner



Gathering Machine – slurries cut ore with seawater and transfers to RALS



Existing Seafloor Trenching and Mining Equipment





RT-1 from SMT facility (contractor for Solwara 1 equipment)



Second generation 200 ton offshore diamond mining machine, DeBeers, Namibia Courtesy Marine Minerals Pty

- 30+ years seafloor trenching for pipelines and communications
- De Beers 20+ years seafloor crawlers for diamond mining
- Utilizing cutting expertize from



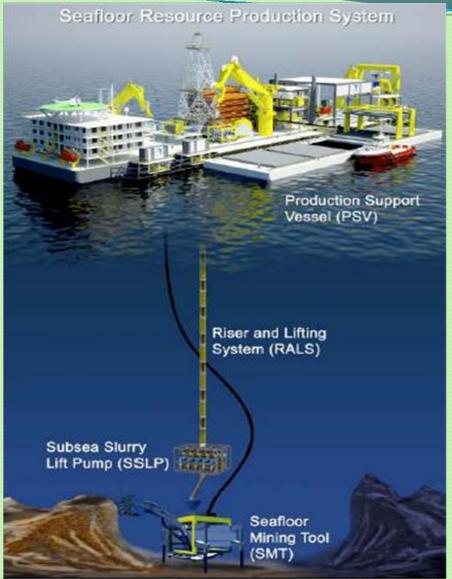


Figure 19-5: Seafloor Resource Production System

"... in the ocean depths, there are mines of zinc, iron, silver and gold that would be quite easy to exploit"

